# ROLE OF MATERIALS IN PERFORMANCE OF PRINTED TEMPERATURE SENSORS

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### **Presentation Outline**

- Application Background
- Why Printed Temperature Sensors
- Sensor Components and Material Properties
- Role of Sensor Materials
- Importance of Manufacturing Processing
- Brewer Science's Printed Temperature Sensors
- Conclusion





### Industry 4.0 Warehousing

Modern warehousing requires more and better environmental control

• Temperature is a key environmental factor to monitor and control

### Why is this?

- Monitors temperature and activates an alarm in response to an undesired condition
- Protects unnecessary damage or loss of inventory and equipment
- Protects warehouses from potential unauthorized access.



Brewer Science Industry 4.0 solutions will support modern warehousing

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### Warehousing Automation Is Rising



Source: 1. Service Level Agreement/ Realstevierichards.com; 2. Tractica

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### Thermal Mapping of Industry 4.0 Warehouses

- Configure sensors into arrays through defined areas of your warehouse
- Monitor temperature condition of different zones of your warehouse





Industry 4.0 Warehouses

Temperature mapping

An accurate and reliable temperature sensor is a key.

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### What's Needed to Accomplish This

- Sensors
- Power
- Design & Hardware
- Software
- Data Transmission
- Data Acquisition and Computing
- Execute



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## Why Printed Temperature Sensors?

- Low-cost, scalable manufacturing
- Unlimited customization
- Flexibility and printability on conformal surfaces
- Configurable into sensor array
- High speed (< 200 ms)
- Direct integration with other sensors for multi-pixel sensing

### **Current Issues**

- Less accurate than existing, commercial temperature sensors
- Some drift over time
- Poor manufacturing yield with current manufacturing practices
- Less matured technology

## Printed Temperature Sensor/Array

#### Sensor components

- Substrate
- Sensing material
- Encapsulant

#### **Key Material Properties**

- Thermal robustness (against degradation, expansion)
- Sensor material inertness to other environmental parameters (e.g. humidity, VOCs, gases, etc.)
- Good thermal conductivity
- Matched thermal expansion between different components



Figure: Temperature sensor array with 16 printed temperature sensors



### **Role of Substrates**

#### Substrate is the largest component of a sensor!

#### **Desired Properties**

- Thermally robust and stable
- Low MVTR
- Inertness to other conditions (e.g. humidity, VOCs, gases, etc.)
- Excellent thermal conductivity
- No outgassing

#### **Cause for Different Performance??**

- Different glass temperature
- Difference in thermal stability, degradation
- Different in inertness at higher temperature



Figure: Substrate degradation with sensor processing



Figure: Performance comparison between sensors, prepared on different substrates





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### **Sensing Material**

#### **Desired Properties**

- Larger response to temperature change (temperature coefficient of resistance- TCR)
- Temperature response linearity
- Thermally robust (against degradation)
- Repeatability in a wide temperature range
- Inertness to other conditions (e.g. humidity, VOCs, gases, bend, etc.)
- Excellent thermal conductivity
- Cause for different performance
  - Different TCR for different materials
  - Residual solvent in printed film
  - Response to other conditions
  - Contact resistance



Figure: Performance comparison of 3 different materials



# Role of Encapsulant

#### **Desired Properties**

- Thermally robust (against degradation and expansion)
- Stable in a wide temperature range
- Good adhesion to substrate and active layer
- Good barrier against undesired environmental conditions (e.g. humidity, VOCs, gases, etc.)
- Excellent thermal conductivity

#### Cause for different performance

- Difference in material thermal properties (Tg, thermal expansion, stability)
- Different solvents and incomplete curing
- Mismatched thermal expansion with substrate and active layer



Figure: Performance comparison of 5 different encapsulants

### Sensor Curing/Processing

- Curing of different components (printed layers)
  - Sensing material
  - Encapsulant
- Thermal break-in of sensors (annealing at higher temperature)
- Processing variables: temperature, time, atmosphere
- Why optimized cure processing and break-in??
  - To eliminate issues with incomplete removal of all solvents
  - To get best out of each material components
  - Thermal break-in at higher temperature eliminates thermal-related stress and drift on sensors during use



# **Curing of Sensing Layer**

- Improved accuracy and TCR with higher cure temperature
- But avoid material degradation and decomposition with extra-high temperature!

#### **Causes for Difference Performance**

- Difference in solvent removal from printed film
- Higher TCR comes from solvent-free conductive film
- Thermal break-in at higher temperature cure releases thermal-related stress from the film



Figure: Performance comparison of same type of sensors cured at different temperatures

# **Curing of Encapsulant**

#### Results

- Higher encapsulant cure temperature: Improved TCR and long-term stability
- However, avoid temperature that can cause material degradation!

#### **Why Difference**

- Residual solvent in printed films
- Completion of thermal-related changes
- Thermal break-in at higher temperature



Figure: Sensor drift at 75C vs. encapsulant cure temperature

### **Processing Atmosphere**

#### **Cure atmosphere conditions**

• Air, vacuum, inert conditions (N<sub>2</sub>)

#### Why Difference

- Air cure: Possible chemical change and material degradation through material oxidation
- Vacuum cure: Different heat transfer process (radiation only)
- Inert atmosphere cure: Efficient heat transfer (convection + radiation) without material oxidation



Figure: Same sensor/substrate cured at different conditions

### Thermal break-in

- Variable: temperature, time, atmosphere
- Improved accuracy and TCR with longer break-in
- Eliminates thermal-related stress from each component of the sensors, and reduces drift during use

350°C Break in	75°C/100 day Drift (°C)
1X	10.5
2X	7.5
5X	3.0



Figure: Sensor break-in duration vs. performance



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### **Brewer Science's Printed Temperature Sensor**

- Resistive-type, printed metal-based
- Accurate; < 0.3°C accuracy for (0°C to 75°C), and ~ 0.6°C for (-20°C to +100°C) range
- Minimal drift over time
- Very fast (175 ms response time measured)
- Hermetically sealed; environmentally stable
- Flexible form factor.



Figure: Sensor response to temperature



Figure: Sensor response to hot oil



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### **Sensor Specifications**

#### Limitations

 Bigger drift at >100°C (about 10°C at 100°C in 100 days). <2°C drift with improved sensing material.

#### Improvements

- Use of more thermally stable sensing material and encapsulant
- Prolonged thermal break-in
- 4-point design to eliminate contact resistance

Parameter	Performance	Unitt
Resistance Value (At 25°C)	200 ± 10%	Ω
Accuracy (0°C to +750°C)	0.3	°C
Accuracy (-20°C to +100°C)	0.6	°C
Accuracy (-40°C to +120°C)	0.8	
Hysteresis (0°C to +75°C)	0.4	°C
Hysteresis (-20°C to +100°C)	0.8	°C
Hysteresis (-40°C to +120°C)	1.1	
Linearity (-40°C to +120°C)	> 99.99	%
Temperature Coefficient of Resistance	~ 3200	ppm/°C
Temperature Sensitivity	< 0.1	°C
Thermal Time Constant (1/e in slow moving air)	175	ms
Recovery time (1/e) *	~1	S
Device Drift At 75°C in 100 days	< 2	°C
At 100°C in 100 days	10	



## Conclusion

- Monitoring temperature in Industry 4.0 warehousing protects unnecessary loss of inventory and equipment damage, and also protects warehouses from potential unauthorized access.
- Printed temperature sensor offers low-cost, scalable manufacturing, with unlimited customization and flexibility
- Choice of right materials and right set of properties is a key to printed sensor performance
- Optimized cure/processing of each printed material and thermal break-in gives best sensor performance



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